

The 20th International Symposium on Nonlinear Acoustics,
Lyon, June 29th, 2015

Nonlinear effects in ultrasound fields of diagnostic-type transducers used for kidney stone propulsion: characterization in water

**M. Karzova,^{1,2} B. Cunitz,³ P. Yuldashev,¹ Y. Andriyakhina,¹
W. Kreider,³ O. Sapozhnikov,^{1,3} M. Bailey,³ V. Khokhlova,^{1,3}**

¹ Department of Acoustics
Physics Faculty
Moscow State University
Russia



² Laboratoire de Mécanique
des Fluides et d'Acoustique
Ecole Centrale de Lyon
France



³ Center for Industrial and
Medical Ultrasound
Applied Physics Laboratory
University of Washington, USA



Outline

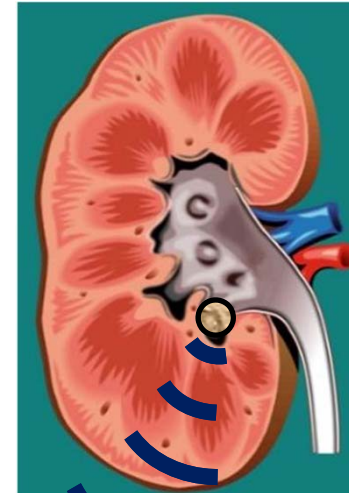
- ❖ Ultrasonic propulsion of kidney stones
- ❖ Pressure saturation was observed at high power levels
Question: what is the mechanism?
Hypothesis to test: nonlinear propagation effects
- ❖ Approach: 3D Westervelt equation to model nonlinear acoustic fields and saturation effects
- ❖ Conclusions

Ultrasonic propulsion of kidney stones

Ultrasonic propulsion system



Pushing residual fragments



2.3 MHz,
Philips C5-2

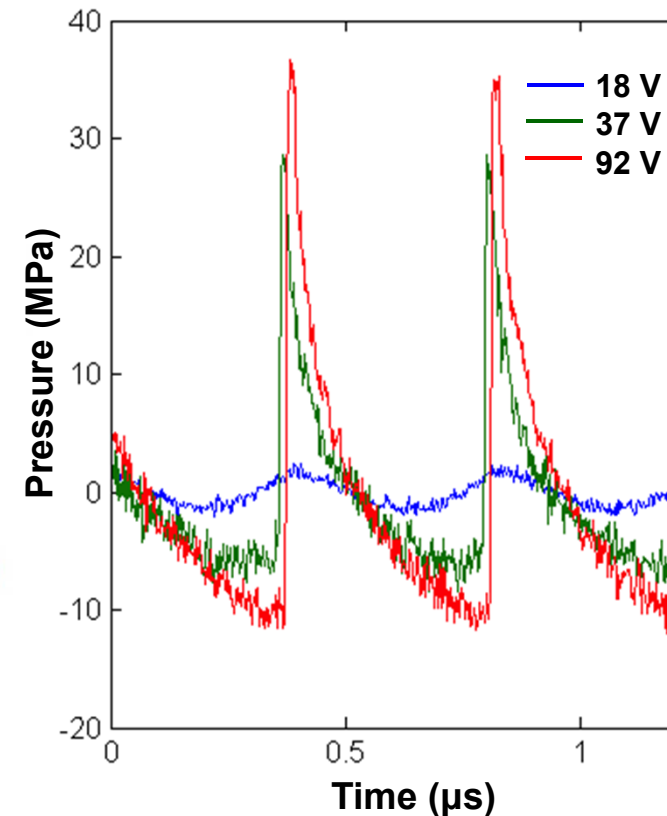
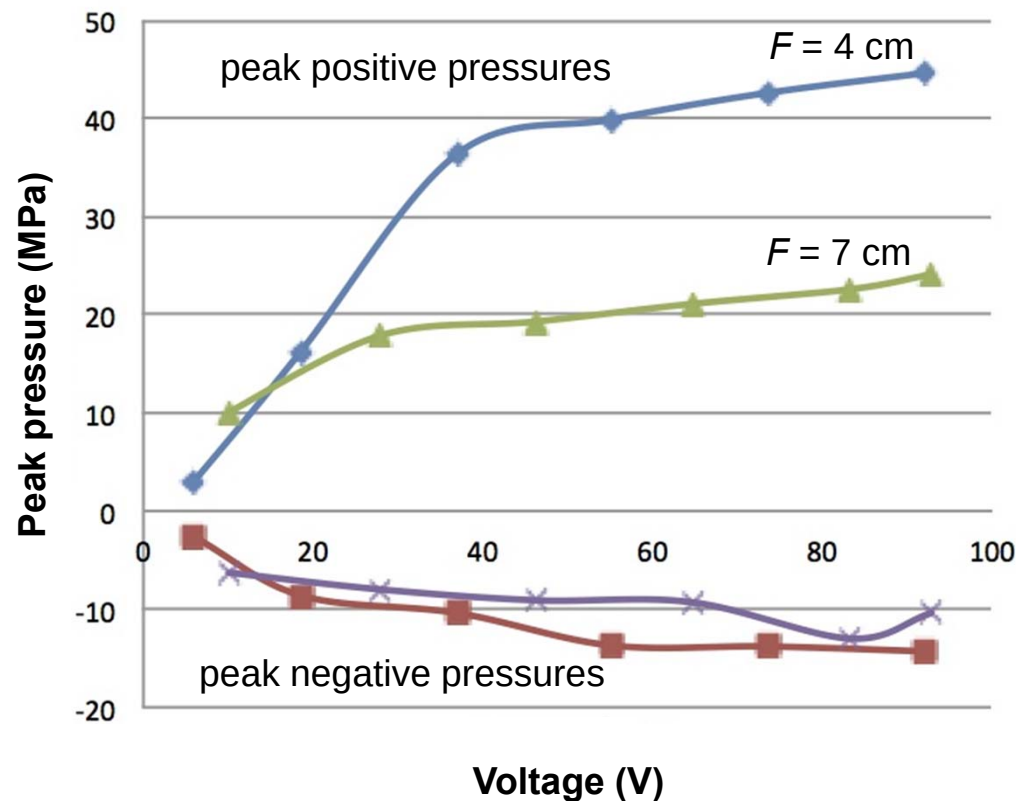
Harper, Bailey *et al.*, J. Endourol.
26 (11), 1494–1499, 2012.

The goal: use ultrasound radiation force to push stone fragments toward the exit of the kidney

Saturation effects observed at high voltages

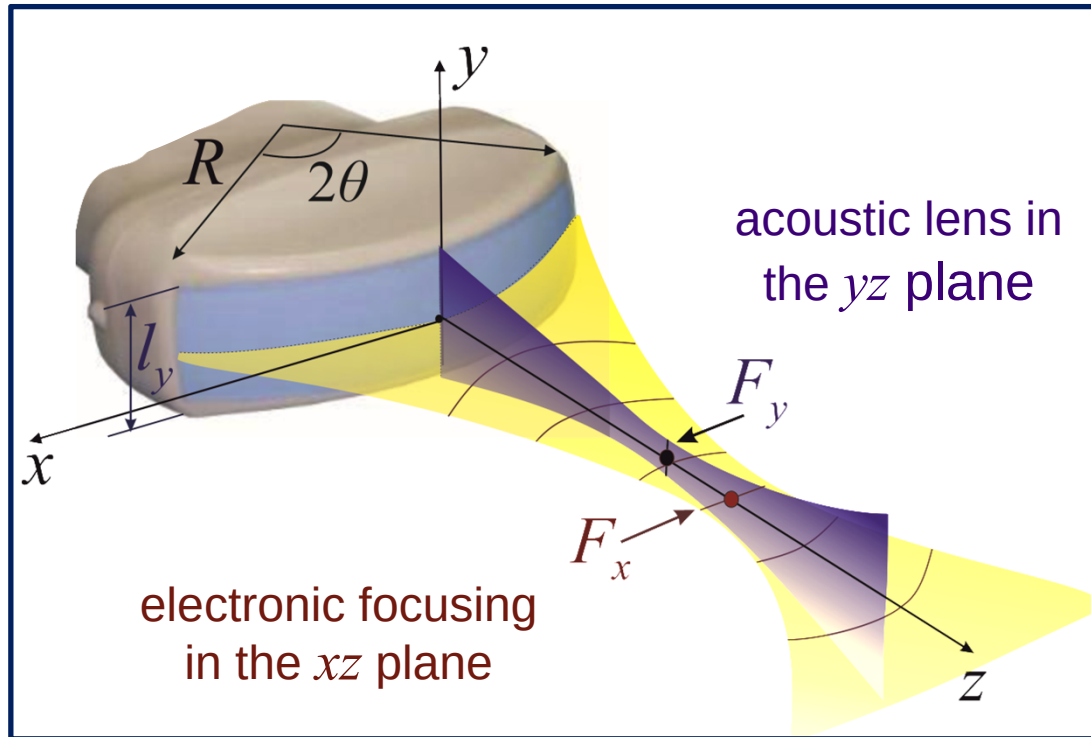


Saturation effects were observed for acoustic pressures in the focal region – what is the reason?



Hypothesis: nonlinear acoustic saturation effect is a limiting factor to provide sufficient radiation force for stone propulsion

Theoretical model



Boundary condition:

- cylindrical surface
- uniform amplitude distribution
- continuous phase distribution
- fitting parameters: $R, \theta, l_y, F_{x,y}$

Parameters:

$R = 38$ mm, $l_y = 12.5$ mm,
 $F_x = 50$ mm, $F_y = 70$ mm

3D Westervelt equation in the retarded time coordinates

$$\frac{\partial^2 p}{\partial \tau \partial z} = \frac{c_0}{2} \left(\frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial y^2} + \frac{\partial^2 p}{\partial z^2} \right) + \frac{\varepsilon}{2\rho_0 c_0^3} \frac{\partial^2 p^2}{\partial \tau^2} + \frac{\delta}{2c_0^3} \frac{\partial^3 p}{\partial \tau^3}$$

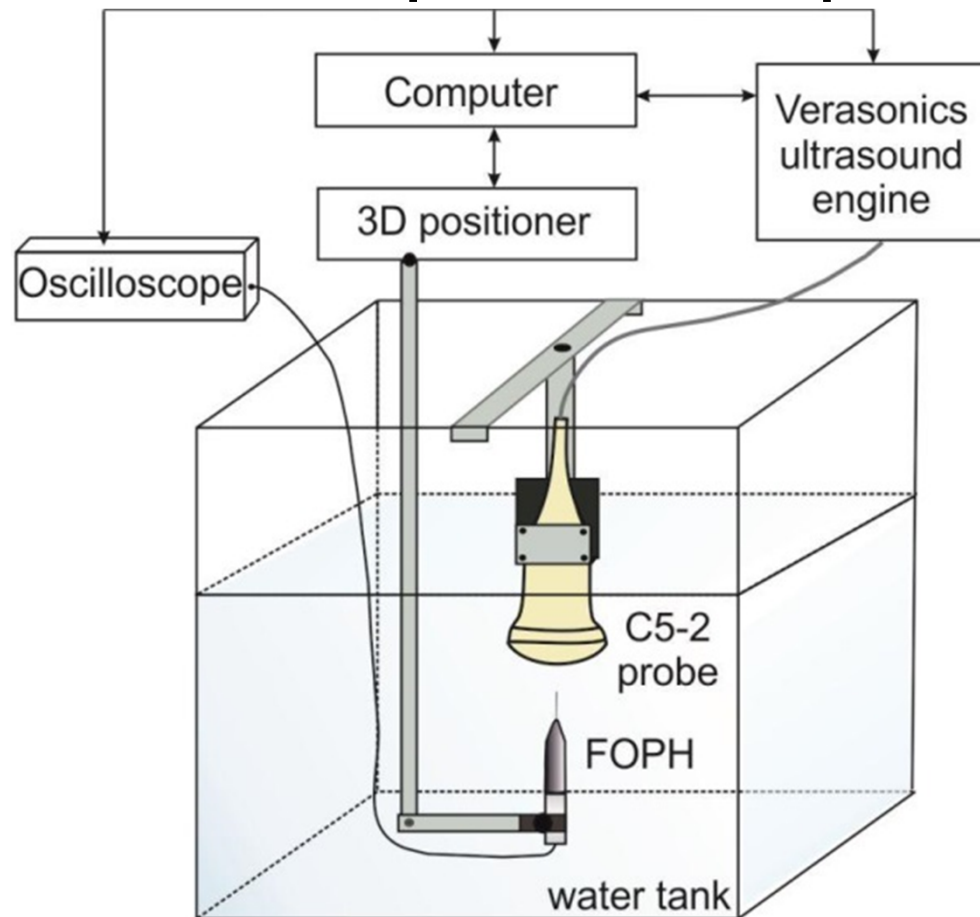
$$\tau = t - z / c_0$$

Combined time-domain and
frequency-domain approach

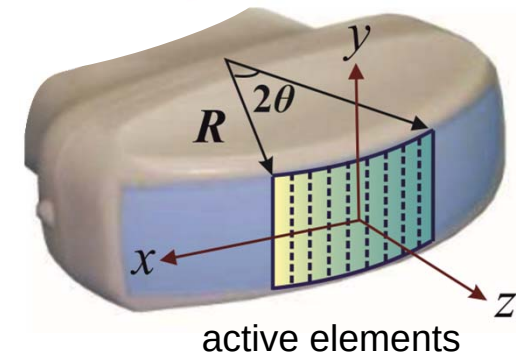
$$p(x, y, z, \tau) = \sum_{n=-N_{\max}}^{N_{\max}} p_n(x, y, z) \exp(-in\omega_0 \tau)$$

Setting a boundary condition using linear scans

Experimental setup



Equivalent source



The 'best fit' parameters:

$R = 38 \text{ mm}$, $l_y = 12.5 \text{ mm}$,

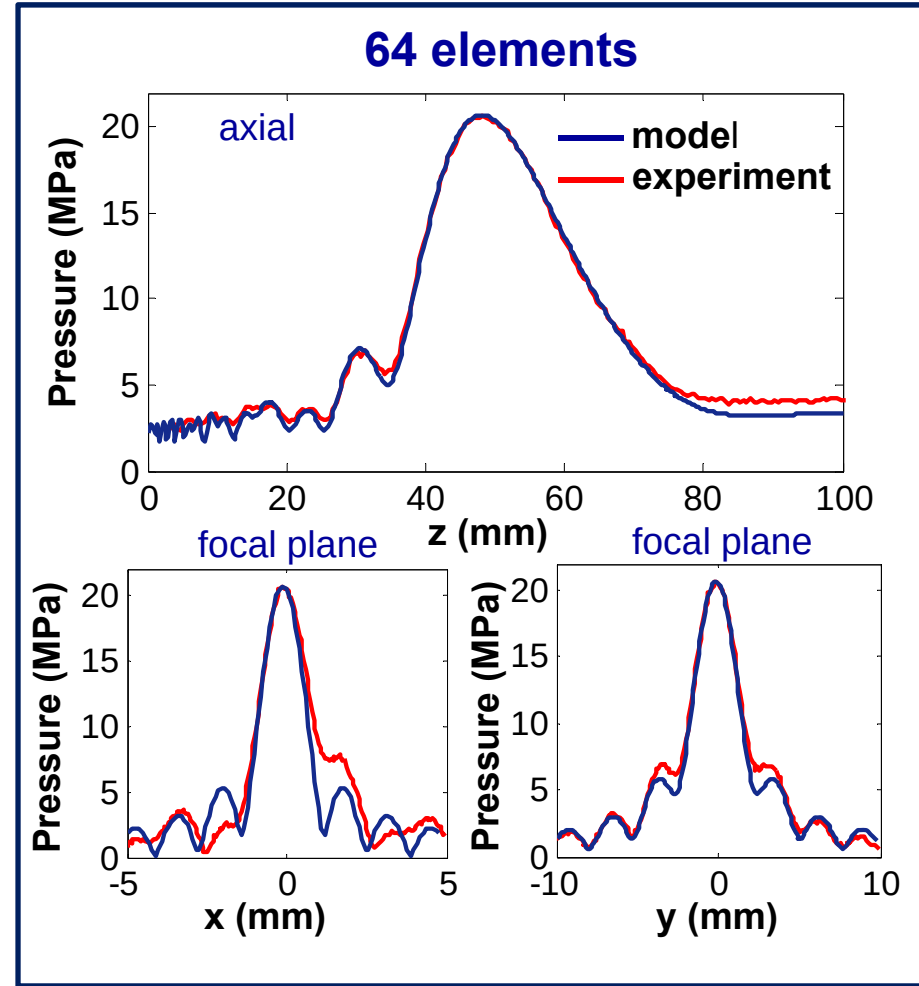
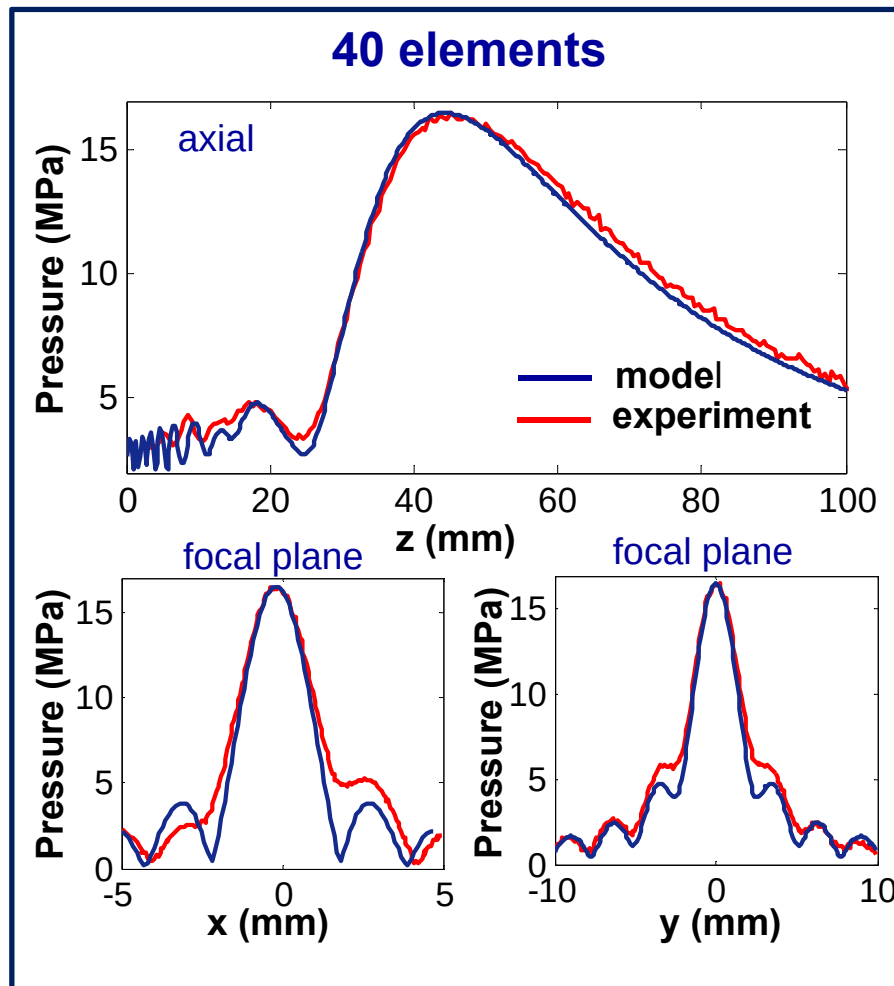
$F_x = 50 \text{ mm}$, $F_y = 70 \text{ mm}$,

$\theta = 0.2N/R$,

$p_0 = 2.75 \text{ MPa}$ for 40 elements,
 2.2 MPa for 64 elements

- Low power measurements on the axis and in the focal plane of the transducer
- Setting the boundary condition by calculating Rayleigh integral to match experimental data

Setting a boundary condition using linear scans



Simulation results are in good agreement with the experimental data

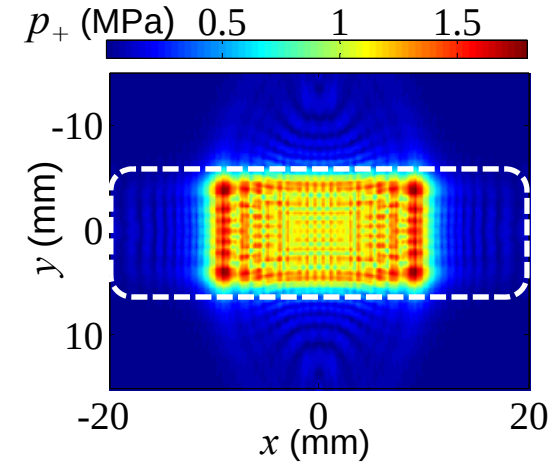
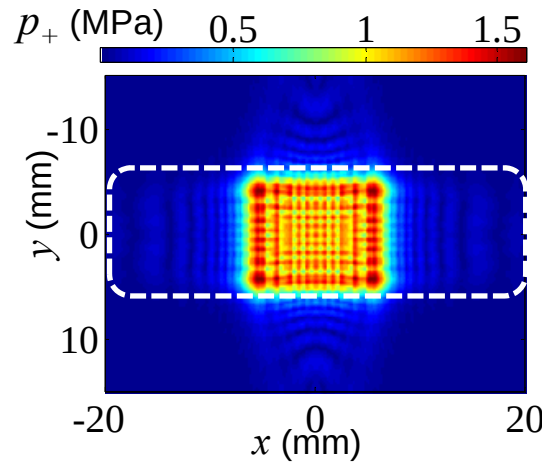
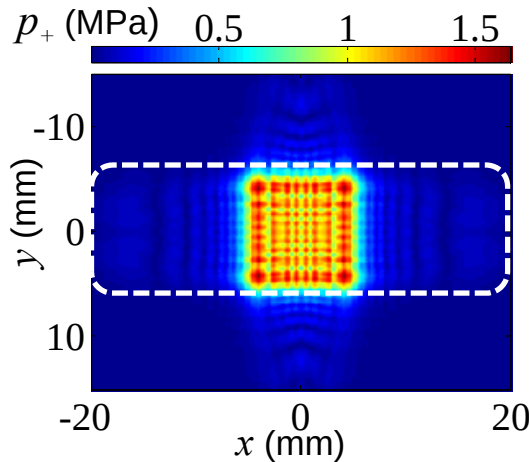
Modeling results: linear case

32 elements

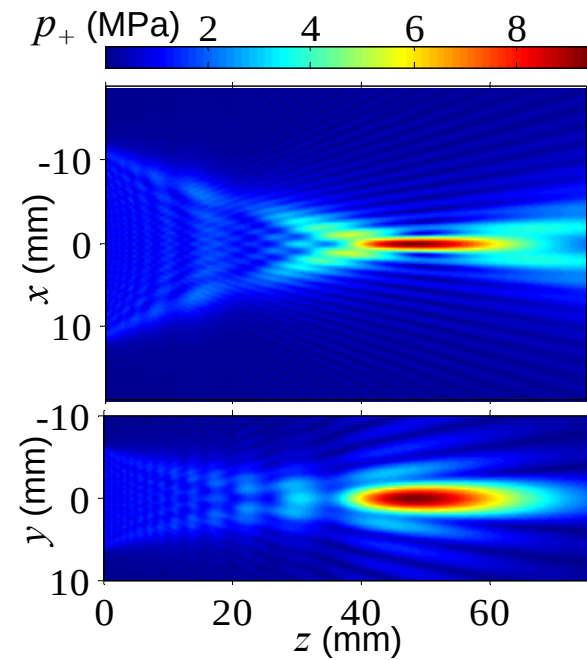
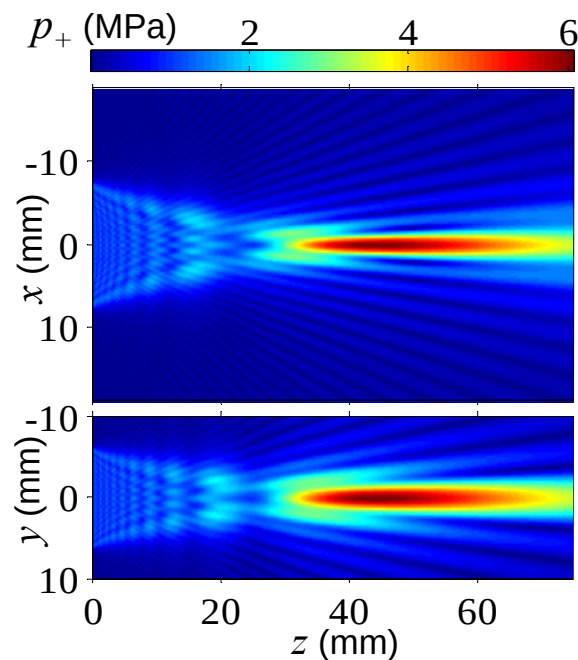
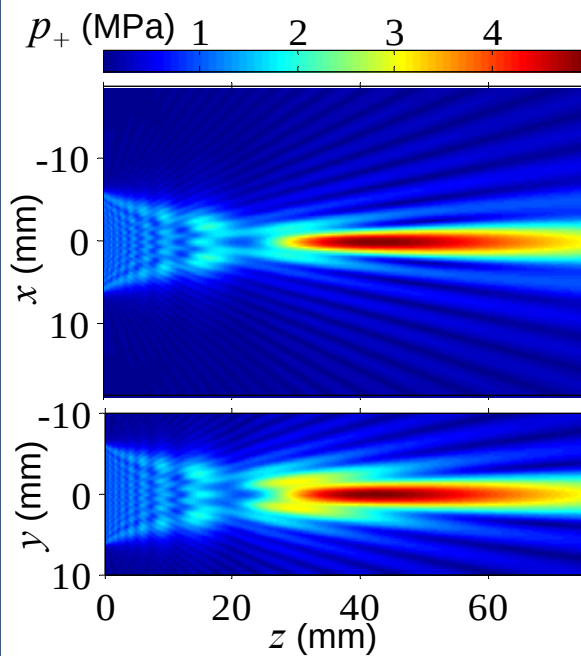
40 elements

64 elements

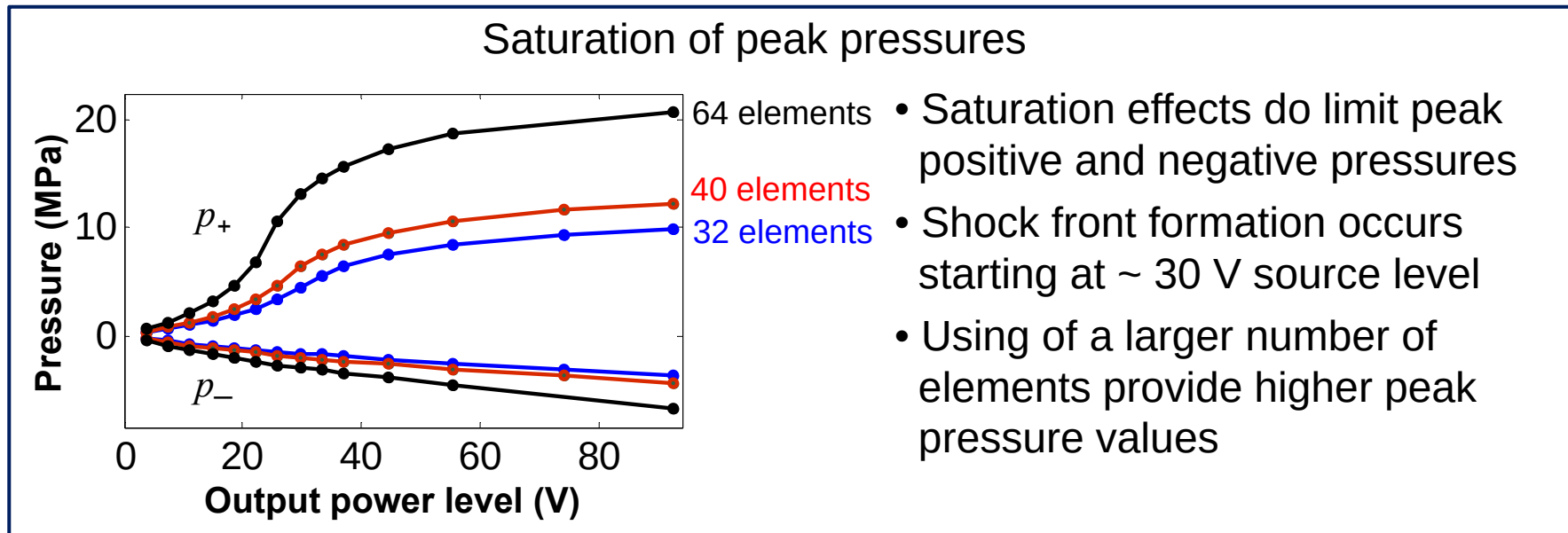
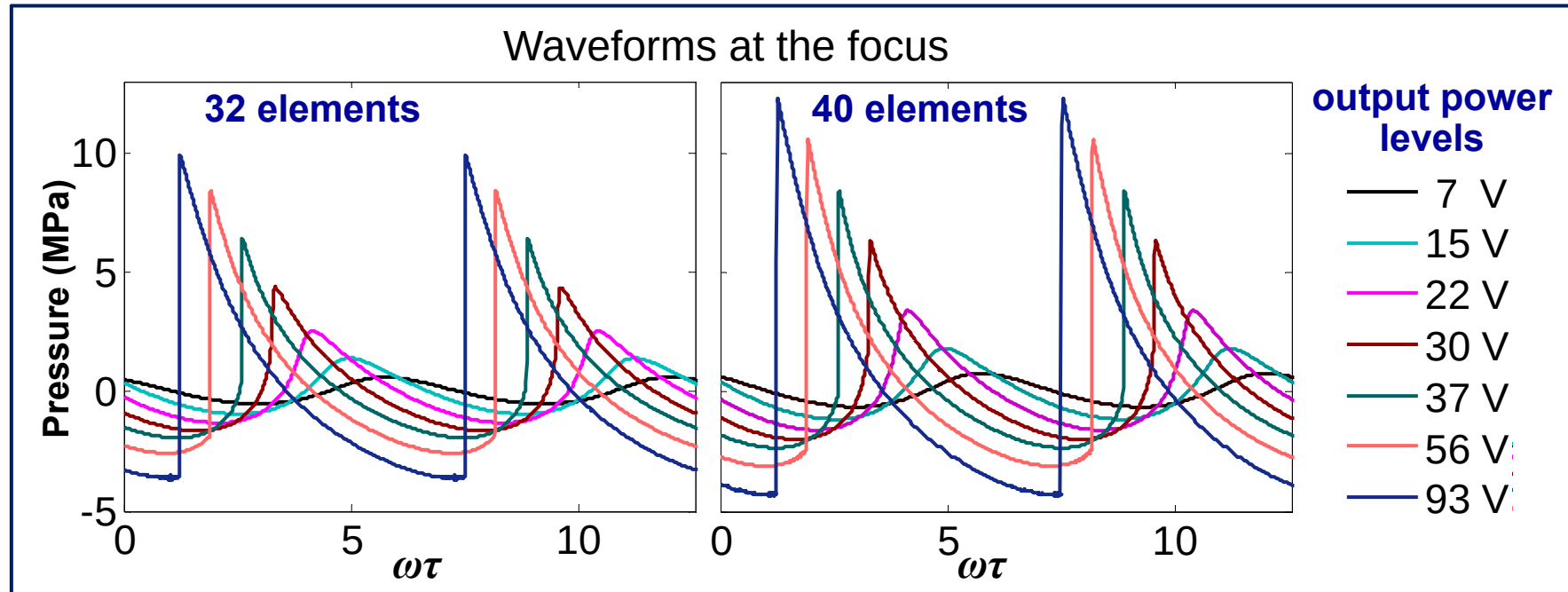
Pressure distributions in the initial plane 2 mm from the transducer



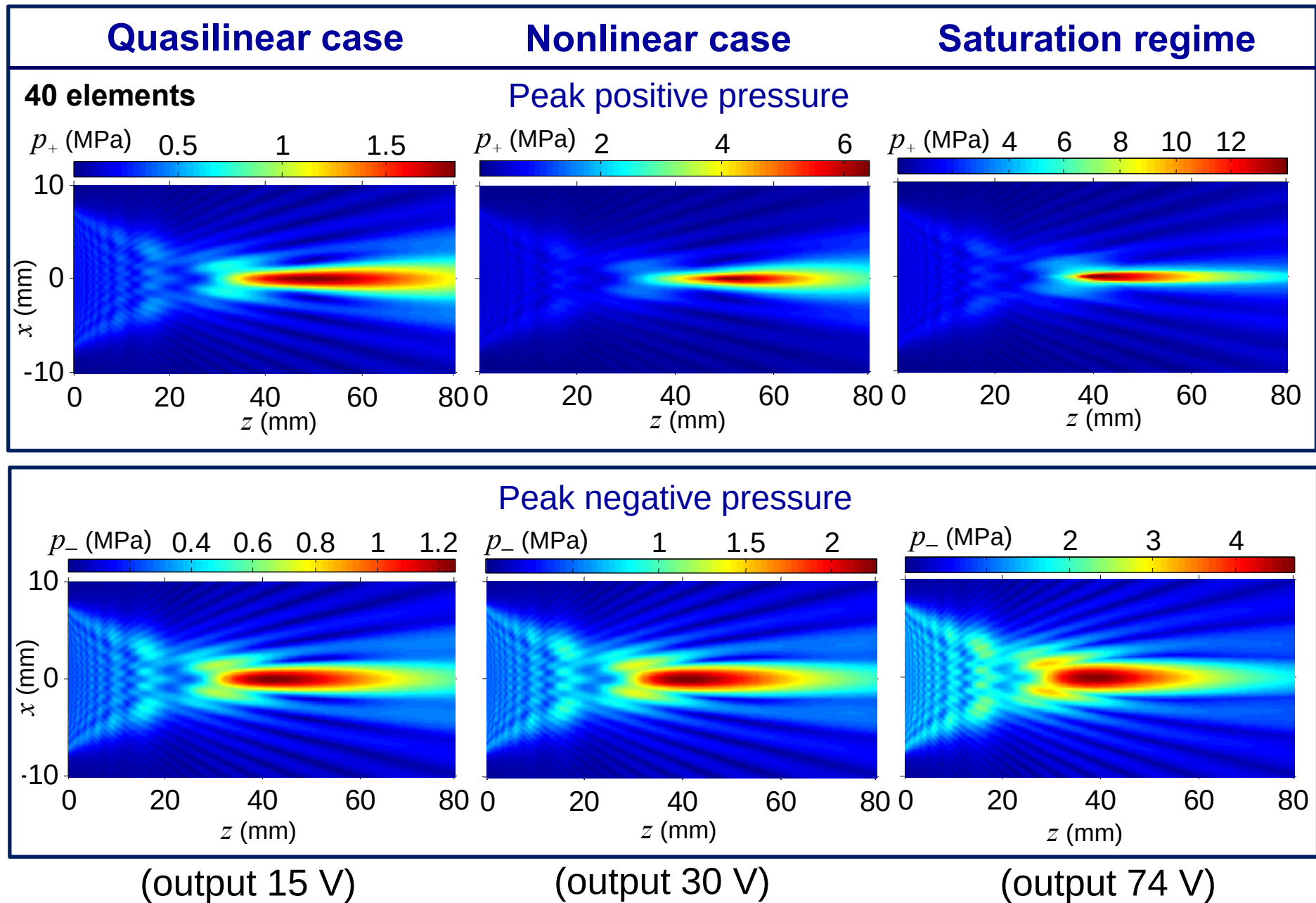
Pressure distributions in the azimuth and elevation planes



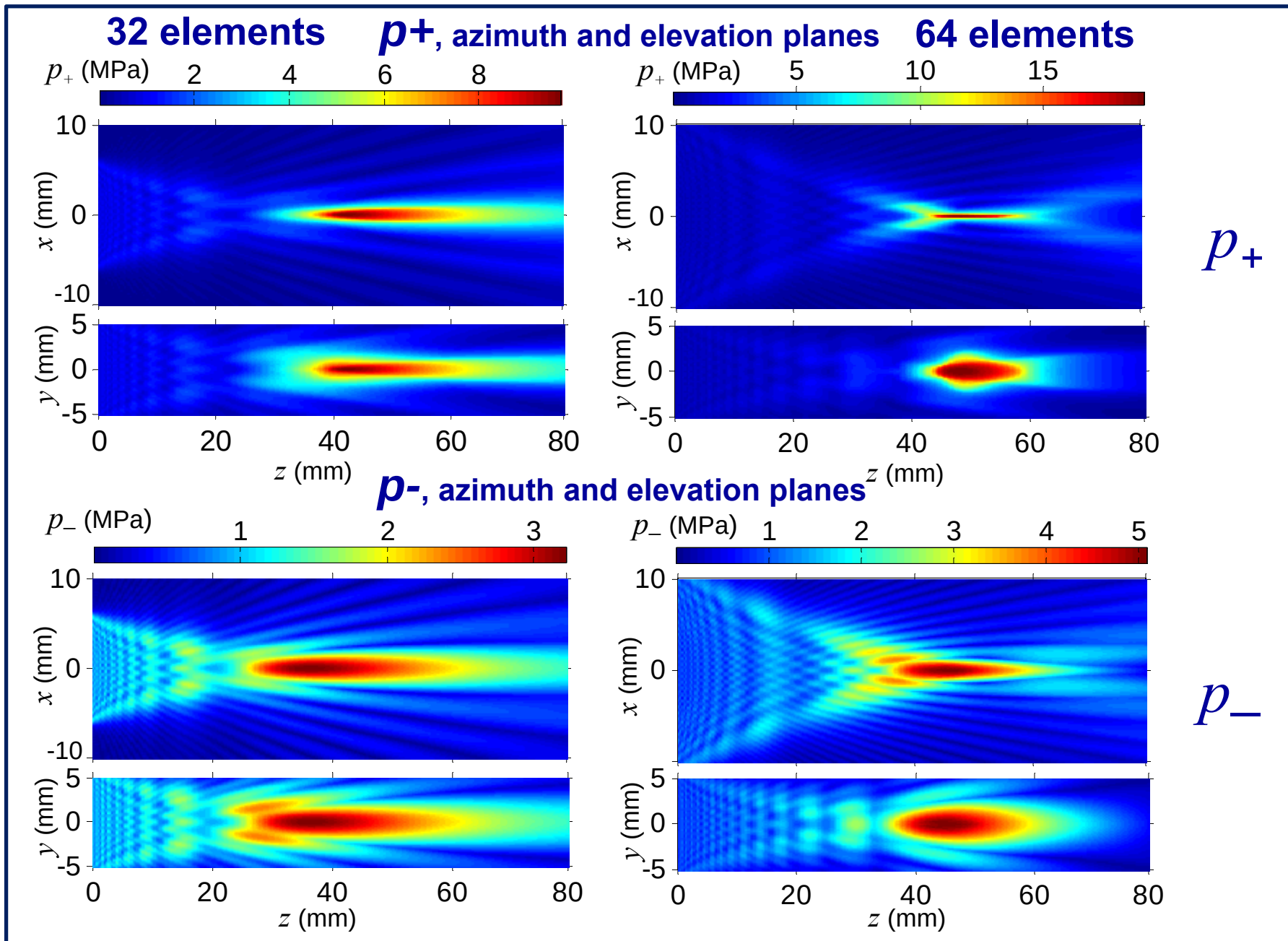
Modeling results: nonlinear propagation



Modeling results: field structure in the elevation plane

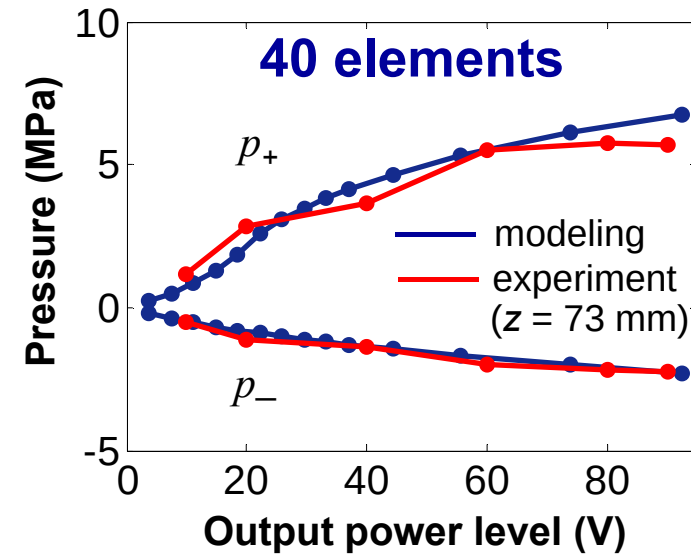
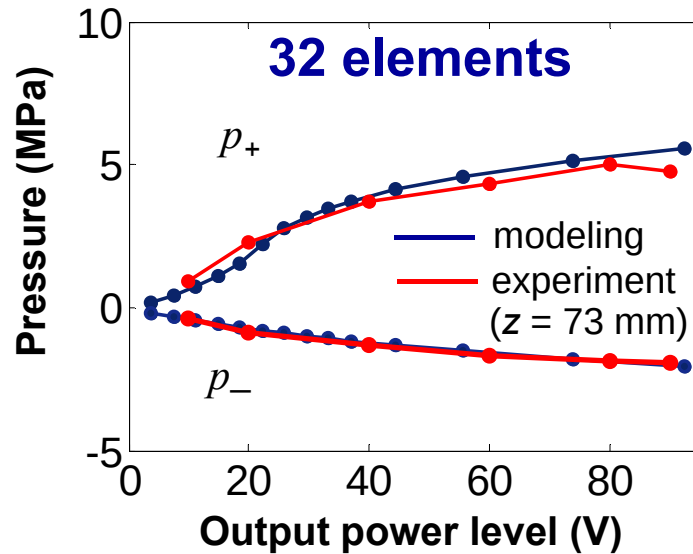


Modeling results: saturation regime (output 56 V)

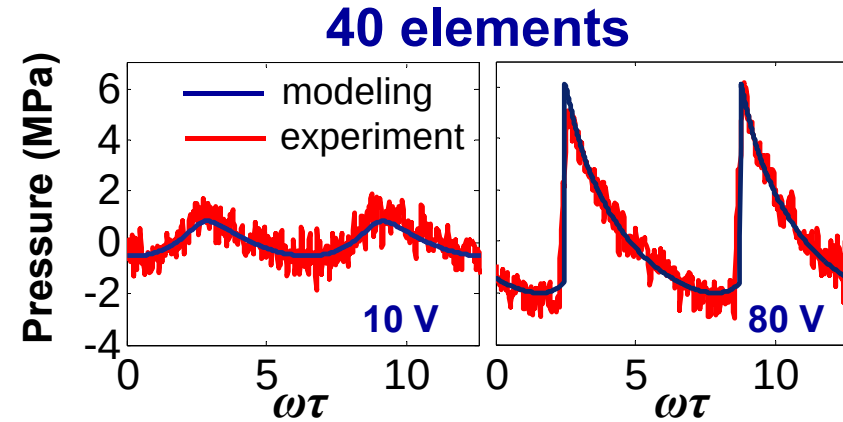
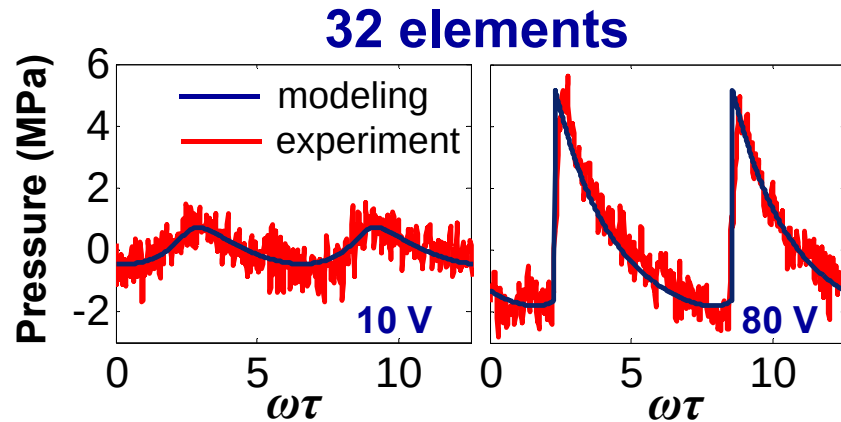


Validation measurements to confirm modeling

Saturation of peak pressures



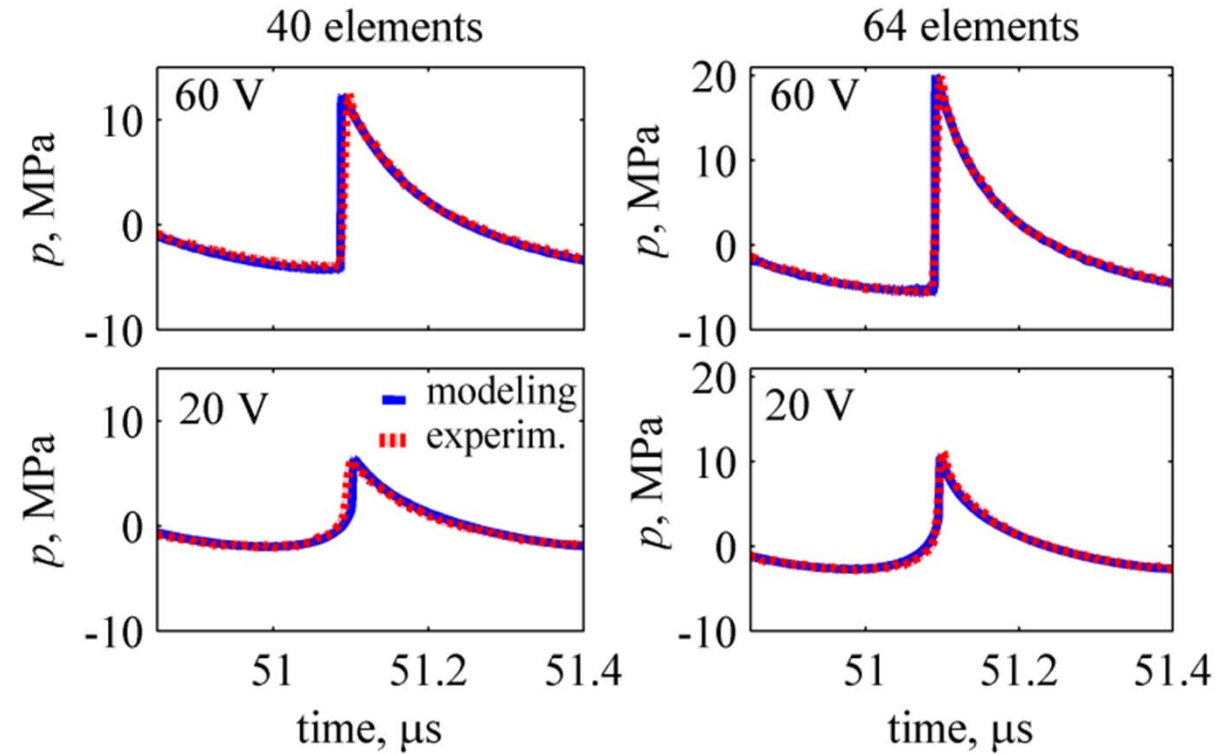
Pressure waveforms



Good agreement between measurements and simulations through a whole range of power outputs

Validation measurements to confirm modeling

Pressure waveforms at $z = 50$ mm



Conclusions

- ❖ Combined measurement and modeling method is capable to calibrate acoustic fields of diagnostic-type transducers (C5-2)
- ❖ Saturation effect limits the peak positive and negative pressures at the focus for stone pushing application outputs
- ❖ Peak positive pressure saturation level is about 20 MPa for 64 active elements and 10 MPa for 32 active elements
- ❖ Shock formation occurs at the output power level about 1/3 (30 V) of the one clinically used (90V)

Future work

Use modeling to optimize transducer parameters for stone propulsion technology

Work supported by NIH EB007643, P01 DK043881, Russian Science Foundation 14-12-00974, and NSBRI through NASA NCC 9-58 NIH